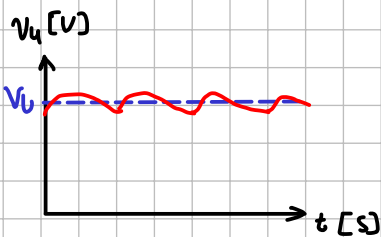
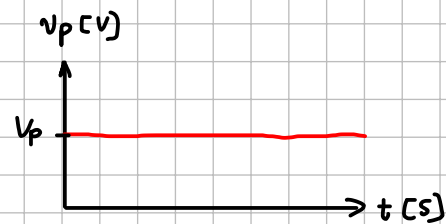


Регулатори напона

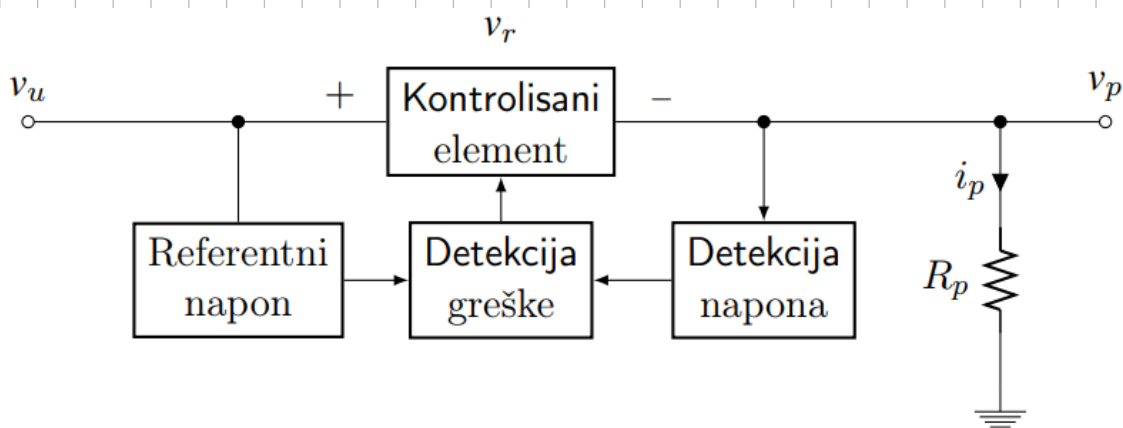


$$v_u = \underbrace{V_u}_{DC} + \underbrace{v_u}_{AC}$$

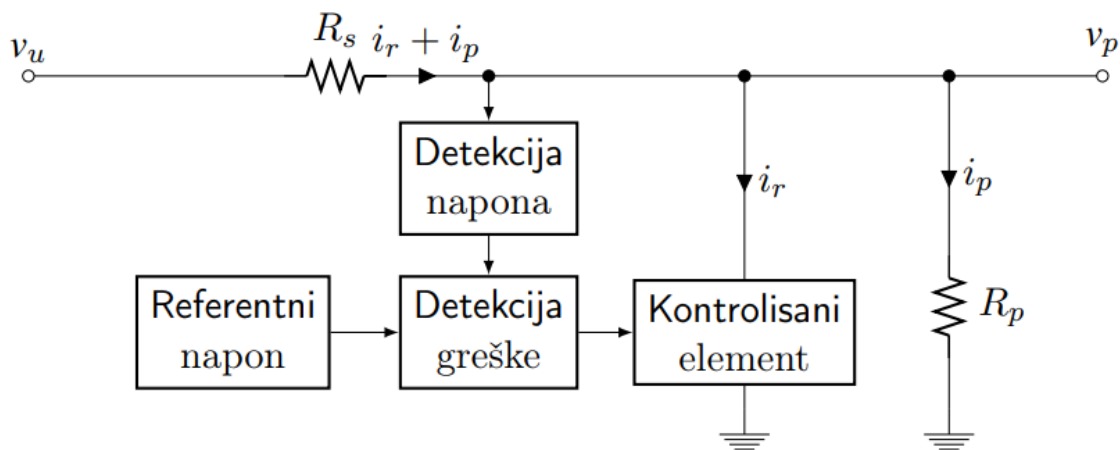
=>



$$v_p = \underbrace{V_p}_{DC} + \underbrace{v_p}_{AC}$$



Блок шема регулатора са редним контролисаним елементом



Блок шема регулатора са паралелним контролисаним елементом

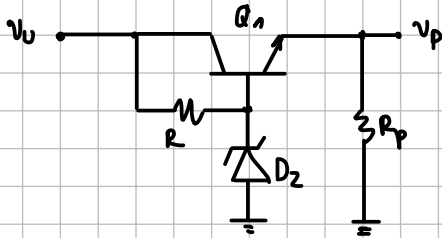
Осетљивост величине x на промену неке величине y :

$$S = \frac{\partial x}{\partial y} \approx \frac{x}{y} \leftarrow \text{мали сигнали}$$

Фактор стабилизације регулатора- осетљивост излазног напона на промене улазног:

$$S_v = \frac{\partial v_p}{\partial v_u} \approx \frac{v_p}{v_u} \leftarrow \text{добија се анализом за мале сигнале}$$

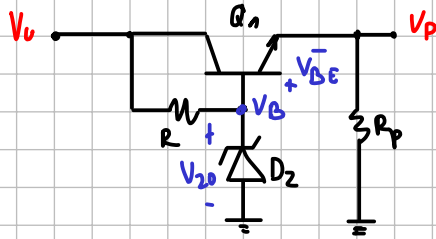
Пр. 1.



Познато је: $R, R_p, V_{z0}, V_{BE}, r_z, g_m, r_{\pi}, V_A \rightarrow \infty$

- a) $V_p = ?$ - Једносмерни излазни напон
 б) $S_v = ?$ - Осетљивост стабилизатора

а) DC:



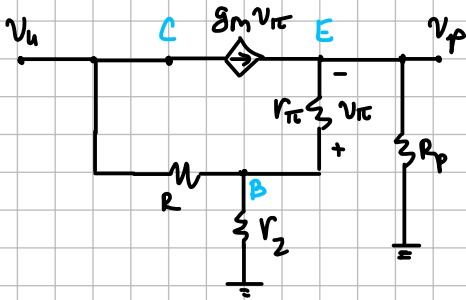
$$v_B - v_p = V_{BE} \quad r_z \approx 0$$

$$v_B = V_{z0}$$

$$v_p = -V_{BE} + V_{z0}$$

д) AC:

$$S_v = \frac{v_p}{v_u}$$



E: $\frac{v_p}{R_p} + \frac{v_p - v_B}{r_{\pi}} - g_m v_{\pi} = 0$

B: $\frac{v_B}{r_z} + \frac{v_B - v_u}{R} + \frac{v_B - v_p}{r_{\pi}} = 0$

Q1: $v_{\pi} = v_B - v_p$

E: $\frac{v_p}{R_p} + \frac{v_p - v_B}{r_{\pi}} - g_m (v_B - v_p) = \left(\frac{1}{R_p} + \frac{1}{r_{\pi}} + g_m\right) v_p - \left(\frac{1}{r_{\pi}} + g_m\right) v_B = 0$

B: $\frac{v_B}{r_z} + \frac{v_B}{R} + \frac{v_B}{r_{\pi}} - \frac{v_p}{r_{\pi}} = \frac{v_u}{R} \Rightarrow \left(\frac{1}{R} + \frac{1}{r_{\pi}} + \frac{1}{r_z}\right) v_B - \frac{v_p}{r_{\pi}} = \frac{v_u}{R}$

$g_{pp} = \frac{1}{R_p} + \frac{1}{r_{\pi}} + g_m \approx \dots$ $g_{BB} = \frac{1}{R} + \frac{1}{r_{\pi}} + \frac{1}{r_z} \approx \dots$

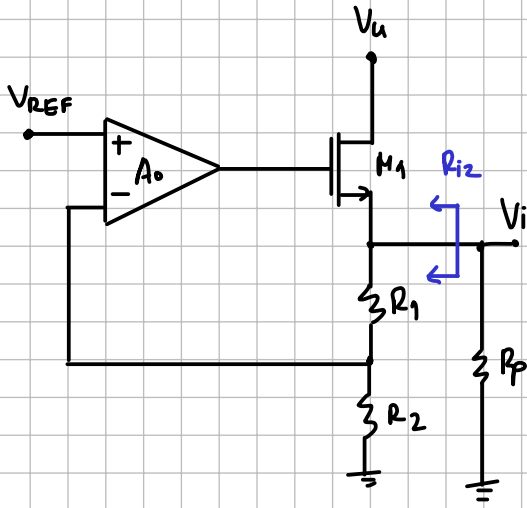
$g_{pB} = -\left(\frac{1}{r_{\pi}} + g_m\right) \approx \dots$ $g_{BP} = -\frac{1}{r_{\pi}} = \dots$

E: $g_{pp} \cdot v_p + g_{pB} \cdot v_B = 0 \Rightarrow v_B = -\frac{g_{pp}}{g_{pB}} \cdot v_p$
 B: $g_{BP} \cdot v_p + g_{BB} \cdot v_B = \frac{v_u}{R}$

$\Rightarrow g_{BP} \cdot v_p + g_{BB} \cdot \left(-\frac{g_{pp}}{g_{pB}} \cdot v_p\right) = \frac{v_u}{R}$

$$\Rightarrow S_v = \frac{v_p}{v_u} = \frac{1}{\left(g_{BP} - \frac{g_{BB} \cdot g_{pp}}{g_{pB}}\right) \cdot R} \approx \dots$$

Пр. 2.



a) $V_i = ?$

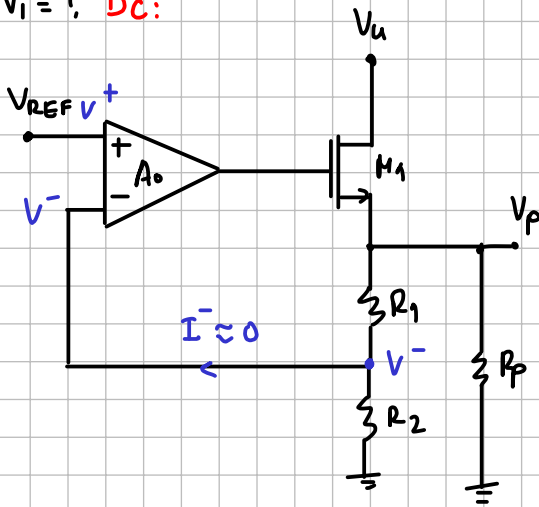
$r_o < \infty$
 A_o, R_1, R_2, g_m

б) $S_v = ?$

в) $R_{i2} = ?$

ОП није идеалан - $R_{L0} \rightarrow \infty$
 $R_{i0} = 0$
 $A_o < \infty$

а) $V_i = ?$, DC:



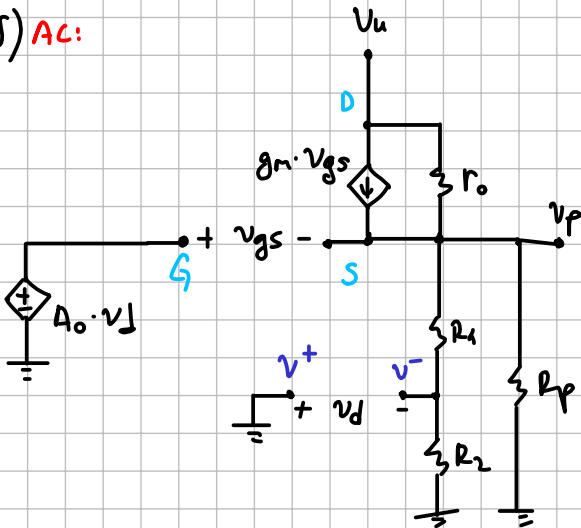
$V^+ \approx V^-$

$V^+ = V_{REF} \Rightarrow V^- \approx V_{REF}$

$V^- = \frac{R_2}{R_1 + R_2} \cdot V_P$

$V_P = \frac{R_1 + R_2}{R_2} \cdot V^- \approx \left(1 + \frac{R_1}{R_2}\right) \cdot V_{REF} \approx \dots$

б) AC:



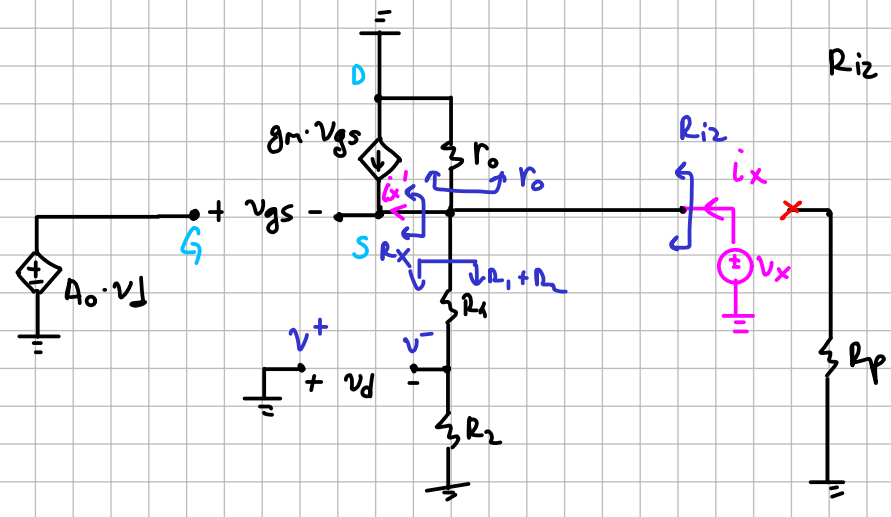
s: $\frac{v_P - v_u}{r_o} + \frac{v_P}{R_1 + R_2} + \frac{v_P}{R_P} - g_m v_{gs} = 0$

$$\left. \begin{aligned} v_{gs} &= A_o \cdot v_d - v_P \\ v_d &= 0 - \frac{R_2}{R_1 + R_2} \cdot v_P \end{aligned} \right\} \Rightarrow v_{gs} = -\left(\frac{A_o R_2}{R_1 + R_2} + 1\right) \cdot v_P$$

$$\left(\frac{1}{r_o} + \frac{1}{R_1 + R_2} + \frac{1}{R_P} + g_m \cdot \left(A_o \frac{R_2}{R_1 + R_2} + 1\right)\right) v_P = \frac{v_u}{r_o}$$

$$S_v = \frac{v_P}{v_u} = \frac{1}{r_o \cdot \left(\frac{1}{r_o} + \frac{1}{R_1 + R_2} + \frac{1}{R_P} + g_m \cdot \left(A_o \frac{R_2}{R_1 + R_2} + 1\right)\right)} = \dots$$

b)



$$R_{iz} = \frac{v_x}{i_x} = ?$$

$$R_{iz} = r_o \parallel (R_1 + R_2) \parallel R_x$$

$$R_x = ?$$

$$R_x = \frac{v_x}{i_x}$$

$$\left. \begin{aligned} i_x' &= -g_m v_{gs} \\ v_{gs} &= A_o \cdot v_d - v_x \\ v_d &= -\frac{R_2}{R_1 + R_2} v_x \end{aligned} \right\} \Rightarrow \begin{aligned} i_x' &= -g_m \left(A_o \cdot \left(-\frac{R_2}{R_1 + R_2} v_x \right) - v_x \right) \\ &= g_m v_x \left(A_o \frac{R_2}{R_1 + R_2} + 1 \right) \end{aligned}$$

$$R_x = \frac{v_x}{i_x'} = \frac{1}{g_m \left(A_o \frac{R_2}{R_1 + R_2} + 1 \right)} \approx \dots \Rightarrow R_{iz} = r_o \parallel (R_1 + R_2) \parallel R_x = \dots$$